Electric Cylinders

EAC Series α_{STEP} AZ Equipped



The motor component incorporates a high-efficiency, energy-saving **QSTEP AZ** Series electric cylinder. In addition to straight-type actuators, reversed motor types with shorter overall lengths are also available.

- Compact, High Strength, for a Wide Variety of **Applications**
- High Performance Regardless of Operating Conditions
- Easy Belt Replacement (Reversed Motor Type)



See Full Product Details Online www.orientalmotor.com

- Manual
- Specifications
- Dimensions

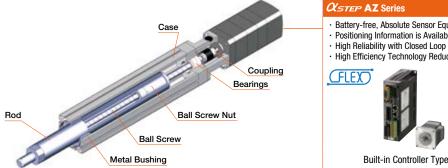
- CAD
- Characteristics
- Connection and Operation

Features

Compact and Powerful!

Compact, High Thrust Force Cylinders

Using aluminum for the rod, these electric cylinders produce high thrust force despite their compact and lightweight body. The unique structure suppresses vibration to achieve improved acceleration characteristics and high-speed positioning operation. This illustration shows a straight type without shaft guide.



OSTEP AZ Series

- · Battery-free, Absolute Sensor Equipped
- · Positioning Information is Available without a sensor
- · High Reliability with Closed Loop Control
- · High Efficiency Technology Reduces Motor Heat Generation and Saves Energy





Selection of Electric Cylinders

Type Name	Product Width × Height	Power Supply Voltage	Lead Screw Pitch [mm]	Stroke [mm]	Maximum Speed [mm/s]		
				100 200 300 400	100 200 300 400 500 600 700 800		
CASTEP AZ Equipped Straight Type Reversed Motor Type	EAC4 42 × 42 mm	Single-Phase 100-120 VAC Single-Phase/Three-Phase 200-240 VAC	12	50~300	600		
			6	 	300		
		24/48 VDC	12	50~300	600		
			6	50~300	300		
	EAC6 60 × 60 mm	Single-Phase 100-120 VAC Single-Phase/Three-Phase 200-240 VAC	12		600		
			6	50~300	300		
		24/48 VDC	12		600		
			6	50~300	300		
CASTEP AZ Equipped Straight Type with Shaft Guide Cover Reversed Motor Type with Shaft Guide Cover	EAC4W 42 × 114 mm	Single-Phase 100-120 VAC Single-Phase/Three-Phase 200-240 VAC	12		600		
			6	50~300	300		
		24/48 VDC	12	50~300	600		
			6		300		
	EAC6W 60 × 156 mm	Single-Phase 100-120 VAC Single-Phase/Three-Phase 200-240 VAC	12	50~300	600		
			6		300		
		24/48 VDC	12	50~300	600		
			6	50~300	300		

^{*}The parentheses () indicate the specifications for the reversed motor type.

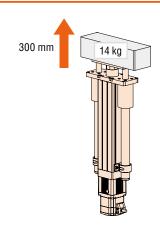
Hybrid Control System *QSTEP* B-77

Capable of a Variety of Movements, Regardless of the Operating Conditions!

Wide Range of Applications, from Low Speed to High Speed and from Light Loads to Heavy Loads

<Product Used> Product name: EAC6WE Lead Screw Pitch: 6 mm Power supply input: 230 VAC

When transferring a load of 14 kg over a distance of 300 mm, the positioning time is 1.12 seconds.



Overview

Linear

Slides **CASTER**

Cylinders *QsтеР* DR\$2

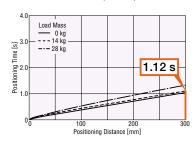
Rotary Actuators OSTEP DGII

USTEP AR

High-Speed With a Heavy Load

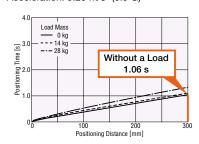
Load Mass: 14 kg

Positioning Distance: 300 mm Positioning Time: 1.12 s Operating Speed: 300 mm/s Acceleration: 2.48 m/s² (0.25 G)



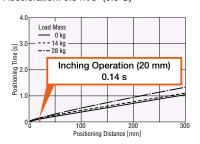
High-Speed With a Light Load

Load Mass: 0 kg Positioning Distance: 300 mm Positioning Time: 1.06 s Operating Speed: 300 mm/s Acceleration: 5.25 m/s2 (0.5 G)



High-Speed During Inching Operation

Load Mass: 14 kg Positioning Distance: 20 mm Positioning Time: 0.14 s Operating Speed: 200 mm/s Acceleration: 5.3 m/s2 (0.5 G)



Positioning Time Calculation Tool Available

A tool is available to calculate the positioning time, operating speed, acceleration, and more — simply by selecting the type of electric cylinder and entering some simple data. The software can be downloaded from the Oriental Motor website. http://www.orientalmotor.com

	Thrust Force	Push Force	Horizontal Transportable Mass [kg]	Vertical Transportable Mass [kg]	Repetitive Reference Positioning	
[N]	[N]	10 20 30 40 50 60 \$ 200 400	10 20 30	Accuracy [mm] Page		
	~70	100	15 7	7		
	~140 (125)*	200	30	4(12.5)*	10.00	
	~70	100	15 7		±0.02	
	~140 (125)*	200	30 1	4(12.5)*		
	~200	400	30 1	15 15 15 15		
	~400 (360)*	500	60 3	30	±0.02	
	~200	400	30 1	15	±0.02	
	~400 (360)*	500	60 3	30	F-24	
	~70	100	15 6		F-24	
	~140 (125)*	200	30 1	3(11.5) *	10.00	
	~70	100	15 6		±0.02	
	~140 (125)*	200	20	3(11.5) *		
	~200	400	30 1	3		
	~400 (360)*	500	60 2	3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3	±0.02	
	~200	400	30 1	3	±0.02	
	~400 (360)*	500	60 2	28		