

Clutch and Brake Motors C•B Motors

Additional Information

Technical Reference	F-1
General Information	G-1

Clutch and Brake Motors

C•B Motors

This compact precision motor is equipped with an internal clutch and brake mechanism for use with a gearhead. This combination makes it the ideal motor for applications involving frequent START/STOP operation, positioning, indexing, jogging and incremental feeding.

Features

Suitable for High-frequency Operation

The combination of a constantly rotating induction motor and a clutch and brake unit enables high frequency starting and stopping.

Compact and Easy to Handle

The compact design simplifies handling and enables the drive unit of the machine to be mounted into a small area.

Characteristics of C•B Motors

The C-B motor is designed so that it runs continuously. This gives the advantage of quicker response time and higher torque in order to move the load.

Output shaft rotation is controlled through the use of the clutch and brake mechanism. The load is stopped by disengaging the clutch and applying the brake. The motor is always affected by the rotor inertia. However, with a clutch and brake unit, the load is not affected by the rotor inertia.



Highly Reliable Gearhead Employed

GC- type and GCH- type gearheads are specifically designed for C-B motors and boast excellent impact resistance, greater strength and high reliability.

For these reasons, C-B motors boast superior response over other AC standard motors, starting and stopping in considerably less time.

To meet high-frequency, starting and stopping applications, Oriental Motor uses an induction motor for its continuous duty rating. An induction motor is best suited for unidirectional movements. The C-B motor is not suitable for frequent bi-directional starting and stopping motion.

Safety Standards and CE Marking (Motor Only)

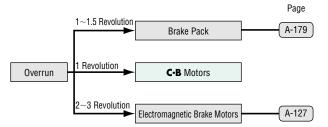
Standards	Certification Body	Standards File No.	CE Marking
UL1004 <u>UL547</u> CSA C22.2 No.100 CSA C22.2 No.77	UL	E64197	Low Voltage Directives
EN60950 EN60034-1 EN60034-5 IEC60034-11	Conform t	Low Voltage Directives	

- Details of Safety Standards→Page G-2
- Motors are recognized by UL. The clutch and brake unit is not UL recognized.
- When the motor is approved under various safety standards, the model name on nameplate is the approved model name.

Other Motor Braking Options

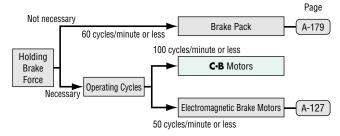
In addition to the brake packs, we provide various brake motors to suit a variety of applications.

- How to Select the Brake Motor
- Selecting from stopping accuracy



* The overrun values are those of an individual motor.

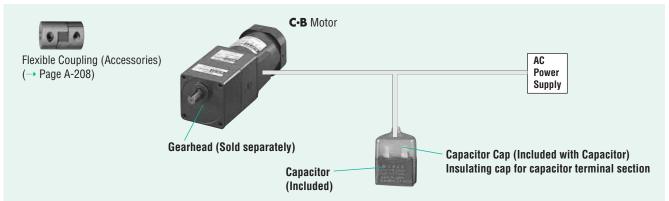
Selecting based on frequency of use



Notes:

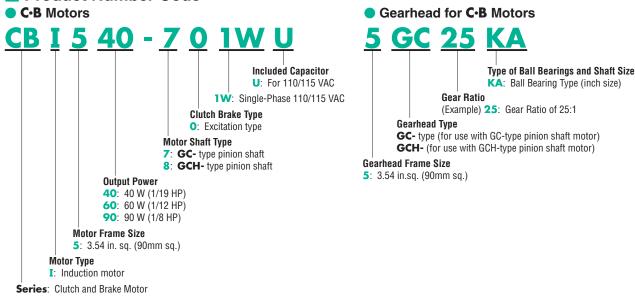
- The operating cycles are based merely on brake response. The value specified above is the maximum, so it may not be possible to repeat braking operation at this frequency.
- In an actual application, be certain the surface temperature of the motor case remains below 194°F (90°C) by considering a rise in motor temperature.

System Configuration



The system configuration shown is an example. Other configurations are available.

Product Number Code



Note:

The "U" at the end of the model name indicates that the unit includes a capacitor.
 This letter is not listed on the motor nameplate.

Characteristics A-175 Dimensions A-177 Connection Diagrams A-178 A-173

Product Line

To select the appropriate C-B motor, consult the output power characteristics on page A-175.

Model Frame	Output I	Power	Voltage	Model	Motor Model	Gearhead Model
Size	HP	W	VAC	Model	WOLDI WOUEI	dearnead woder
3.54 in.sq.	1/19	40	Single-Phase 110/115	CBI540-701WU	5IK40GN-AW-CB1	5GC□KA (Sold Separately)
(90 mm sq.)	1/12	60	Single-Phase 110/115	CBI560-801WU	5IK60GU-AW-CB1	5GCH □ KA (Sold Separately)
(**************************************	1/8 90 Single-Phase 110/115		CBI590-801WU 5IK90GU-AW-CB1		SOCHLINA (Sold Separately)	

- Enter the gear ratio in the box (□) within the model name.
- The GC- and GCH- type gearheads are designed specifically for use with the C-B motor. Other types of gearheads should not be used.
- The clutch and brake unit is not sold separately from the motor.

Specifications

Motor Specifications—Continuous Rating



	Model		Power	Voltage	Frequency	Current	Rated Speed	Capacitor
	Wodol	HP	W	VAC	Hz	А	r/min	μF
	CBI540-701WU	1/19	40	Single-Phase 110	60	0.68	1500	9
(IP)	® CBI540-701WU	1/19	40	Single-Phase 115	00	0.67	1300	J
- TD	P CBI560-801WU 1/12		60	Single-Phase 110	60	1.09	1450	18
(IP)	® CBI560-801WU 1/12	1/12	00	Single-Phase 115	00	1.10	1430	10
- TD	(TP) CBI590-801WU 1		90	Single-Phase 110	60	1.45	1500	20
(P)	® CBI590-801WU	1/0	1/8 90	Single-Phase 115	00	1.44	1500	20

r Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops. When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

Clutch/Brake Specifications

Model Frame	Clutch/Droke	Holding Bı	rake Torque	Voltage	Input W	Cycle Rates
Size	Clutch/Brake	oz-in	mN⋅m	VDC	(at 68°F (20°C))	time/minute
3.54 in.sq.	Clutch	210	1500	24	8.4	100
(90 mm sq.)	Brake	210	1500	24	6.2	100

General Specifications

(At rated motor operation under normal ambient temperature and humidity.)

Item	Specifications
Insulation Resistance	$100M\Omega$ or more when 500 VDC is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5 kV at 60 Hz applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity for 1 minute.
Temperature Rise	144°F (80°C) or less measured by the resistance change method after rated motor operation with a gearhead.
Insulation Class	Class B [266°F (130°C)]
Ambient Temperature Range	$14^{\circ}F \sim 104^{\circ}F (-10^{\circ}C \sim +40^{\circ}C)$ (nonfreezing)
Ambient Humidity	85% maximum (noncondensing)
Degree of Protection	IP20

Permissible Overhung Load and Permissible Thrust Load

		Permissible 0	Permissible	
Model	Gear Ratio	0.39 in.(10 mm) 0.79 in.(20 mm)		Thrust I oad
	deal Hallo	from shaft end	from shaft end	Till dot Load
5GC□KA	3.6∼18	56 (250)	78 (350)	22 (100)
JGC_KA	30~180	67 (300)	101 (450)	22 (100)
	3.6∼9	90 (400)	112 (500)	
5GCH□KA	15~18	101 (450)	135 (600)	33 (150)
	30~180	112 (500)	157 (700)	

[•] Enter the gear ratio in the box (
) within the model name.

Gear Ratio and Speed Range

Unit = r/min

Gear Ratio	3.6	6	9	15	18	30	36	60	90	120	180
60 Hz	500	300	200	120	100	60	50	30	20	15	10

[•] The speed is calculated by dividing the motor's synchronous speed (60 Hz: 1800 r/min) by the gear ratio. The actual loaded speed is 2~20% less than the displayed value, depending on the amount of the load.

Output Power Characteristics

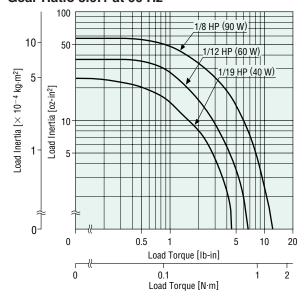
The most appropriate **C-B** motor may be determined by load torque and load inertia requirements of the motor and gearhead using the output selection charts below.

The curves represent the relationship between load torque and load inertia for a minimum of two million starts and stops. The motor should be operated inside the limits of the load torque-load inertia curves given.

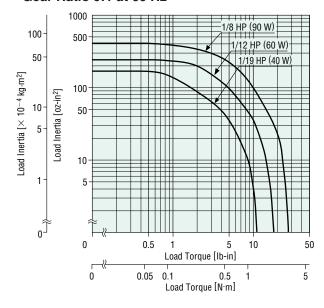
Find the clutch and brake motor best suited for your application as follows:

- ① Determine the maximum load torque required at the gearhead output shaft.
- ② Calculate the reflected load inertia effective at the gearhead output shaft.
- ③ Plot the values found in ① and ② into the graph of the applicable speed. The motor model whose characteristic curve is the closest and above the point you entered is the most suitable motor for your purpose.

Speed at Output Shaft: 500 r/min Gear Ratio 3.6:1 at 60 Hz



Speed at Output Shaft: 200 r/min Gear Ratio 9:1 at 60 Hz



Selection Example

Required Speed: 300 r/min

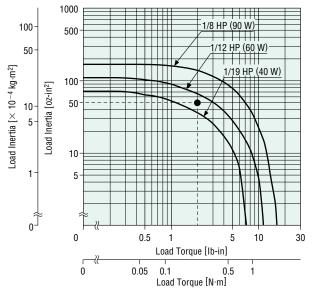
• Load Torque: 2 lb-in

Load Inertia: 50 oz-in²

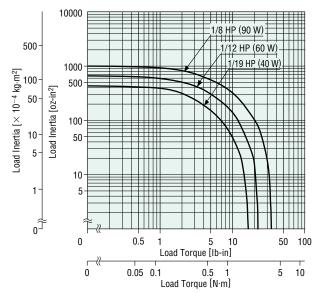
As an example, the value corresponding to the these operating requirements has been marked in the application graph for 300 r/min.

• The speed indicated is calculated by dividing the motor synchronous speed (1800 r/min at 60 Hz) by the speed reduction ratio. Note that depending on the load, the actual speed may be 2~20% lower than indicated in the graph.

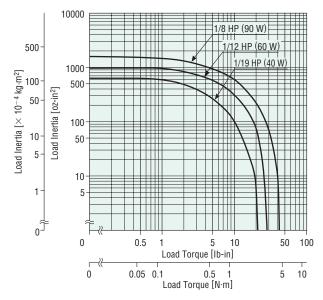
Speed at Output Shaft: 300 r/min Gear Ratio 6:1 at 60 Hz



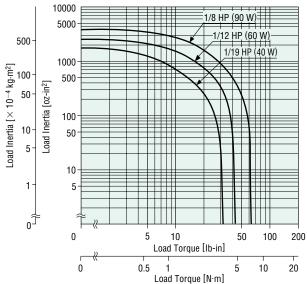
Speed at Output Shaft: 120 r/min Gear Ratio 15:1 at 60 Hz



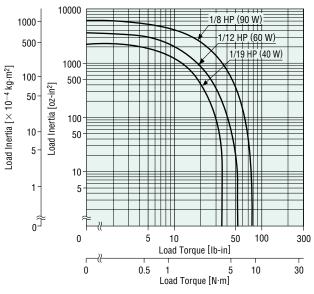
Speed at Output Shaft: 100 r/min Gear Ratio 18:1 at 60 Hz



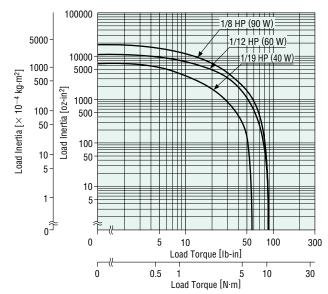
Speed at Output Shaft: 60 r/min Gear Ratio 30:1 at 60 Hz



Speed at Output Shaft: 50 r/min Gear Ratio 36:1 at 60 Hz



Speed at Output Shaft: 30 r/min or slower Gear Ratio 60:1 or greater at 60 Hz



Note:

• When using a C-B motor at an output shaft speed of less than 30 r/min (when using with gearheads of speed reduction ratios greater than 60:1 at 60 Hz), refer to output selection chart entitled "30 r/min or slower."

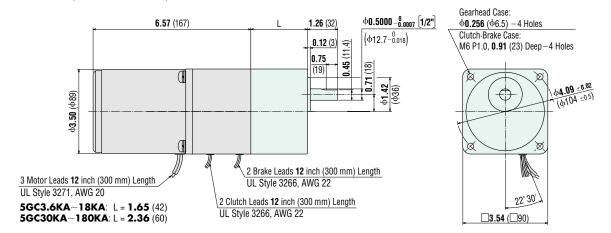
Dimensions Scale 1/4, Unit = inch (mm)

Mounting screws are included with gearheads. Dimensions for screws→A-223

Motor Gearhead 5GC□KA

Weight: 8.4 lb. (3.8 kg) / Weight: 3.3 lb. (1.5 kg)

DXF A261AU (**5GC3.6KA-18KA**) A261BU (**5GC30KA-180KA**)



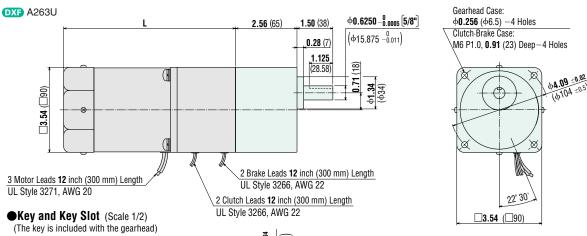
Motor Gearhead SGCH□KA

Weight: 8.8 lb. (4.0 kg) / Weight: 3.3 lb. (1.5 kg)

DXF A262U

CBI590-801WU / 5GCH KA
Weight: 9.9 lb (4.5 kg) / Weight: 3.3 lb (

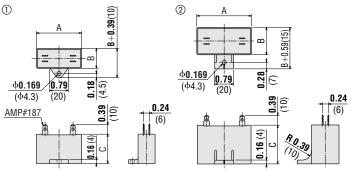
Weight: 9.9 lb. (4.5 kg) / Weight: 3.3 lb. (1.5 kg)



(The key is included with	the geatheau)	7 <u> </u>
(58.28 ±0.5) 1.1875 = 0.008 (58.28 ±0.5) 1.1875 = 0.0042 (7.1875	0.1875 -0.0012 (4.763 -0.03)	0.1875 +0.0016 (4.763 +0.040) (4.763 +0.040)

Motor Model Type	L
Wotor Woder Type	inch (mm)
CBI560-801WU	7.17 (182)
CBI590-801WU	7.76 (197)

Capacitor (included with the C⋅B motor) Unit = inch (mm)

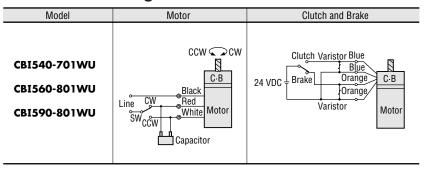


Capacitor	Dimer	isions in.	(mm)	Weight	No.
Model	Α	В	С	oz. (g)	IVO.
CHOOCEVIII	1.89	0.83	1.22	1 // (//)	•
CHAOCIAOL	(48)	(21)	(31)	1.4 (40)	1)
CH180CFAUL	2.28	0.93	1.46	2.5 (70)	<u> </u>
	(58)	(23.5)	(37)		2
CHOOCEALII	2.28	1.14	1.61	3 // (05)	<u> </u>
CHZOOCFAUL	(58)	(29)	(41)	J.4 (3J)	2
	· ·	Model A CH90CFAUL 1.89 (48) CH180CFAUL 2.28 (58) CH200CFAUL 2.28	Model A B CH90CFAUL 1.89 0.83 (48) (21) CH180CFAUL 2.28 0.93 (58) (23.5) CH200CFAUL 2.28 1.14	Model A B C CH90CFAUL 1.89 0.83 1.22 (48) (21) (31) CH180CFAUL 2.28 0.93 1.46 (58) (23.5) (37) CH200CFAUL 2.28 1.14 1.61	Model A B C oz. (g) CH90CFAUL 1.89 0.83 1.22 1.4 (40) (48) (21) (31) 1.4 (40) CH180CFAUL 2.28 0.93 1.46 2.5 (70) CH200CFAUL 2.28 1.14 1.61 3.4 (95)

If you need to order a capacitor without a motor, add "-C" to the capacitor model name shown.

A capacitor cap is included with the capacitor.

Connection Diagrams



- The direction of motor rotation is as viewed from the shaft end of the motor.
- How to connect a capacitors → Page A-225
- The surge absorber circuit is included with the C-B motor.
- Clutch and brake coil lead wires are non-polar.

Notes:

- Change the direction of motor rotation only after bringing the motor to a stop. If an attempt is made to change the direction of
 rotation while the motor is rotating, the motor may ignore the reversing command or change its direction of rotation after some delay.
- When using C-B motors, a 24 VDC power supply for the clutch and brake is required in addition to the motor power supply.
- Transformer capacity on the DC power supply should be at least 1.3 times the rated power consumption of the clutch and brake.
- Be sure to use full-wave rectified DC power supply.
- Do not try to activate clutch and brake simultaneously. When shifting from clutch to brake or vice versa, leave a time lag of at least 20 ms.

• Inner Connection Diagram for 4-Terminal Capacitor

Terminals of the capacitor are connected as shown in the figure. For lead wire connection, use one lead wire per terminal.

